

## Smart motor driver with embedded Hall sensor

### Features

- Motor driver with high sensitivity Hall-effect sensor
- H-Bridge MOS driver
- Lock-shutdown protection & auto-restart function
- “Soft-switch” phase-switching technique to reduce vibration and acoustic noise
- Thermal shutdown protection(TSD)
- Available in SIP-4L package
- For 12V or 24V DC motor / FAN systems


**Halogen Free**

### General Description

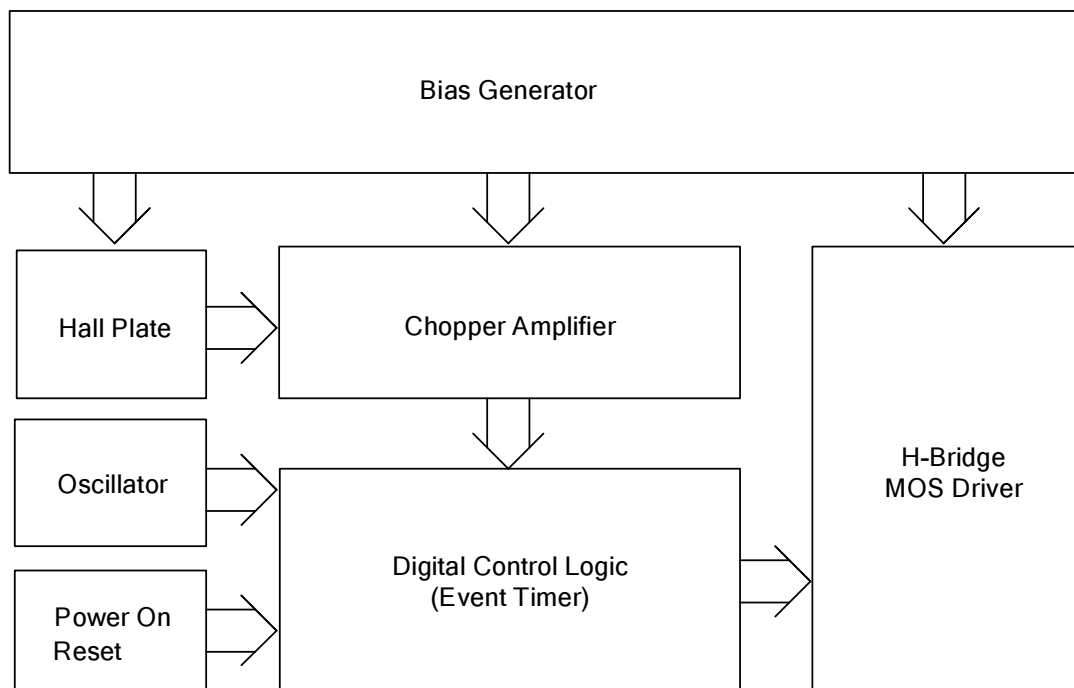
FD2257H is a single-phase full wave motor driver with embedded Hall-effect sensor IC. It integrates a H-bridge MOS driver, a high sensitivity hall-effect sensor, an event timer for rotor locked in SIP-4L package, which make the motors' PCBs(printed circuit boards) design easy and fabricate the high efficiency and high voltage DC motors or FANs as simply as possible.

For safety, Lock-shutdown function would turn the IC's internal drivers off avoiding over-heat when the rotor is locked, and IC will try to re-start the rotor's torque after the time of these drivers' shutdown.

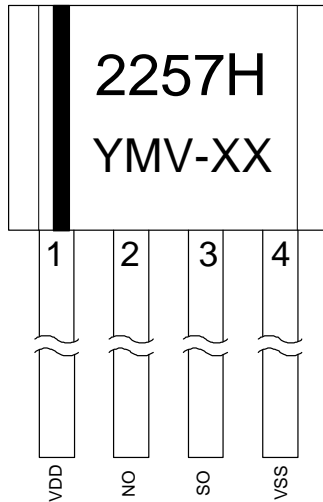
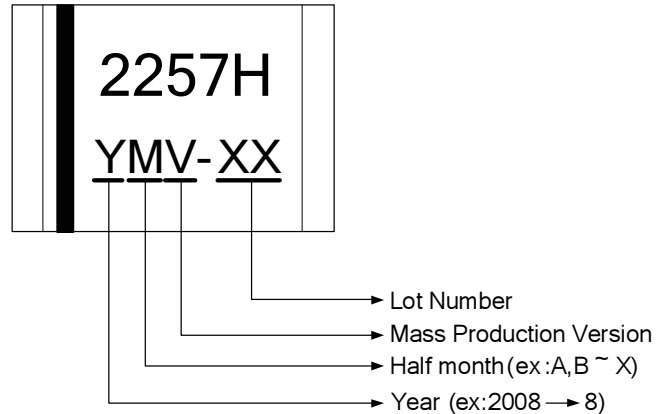
Thermal-shutdown protection (TSD) ensures the internal drivers of IC are operating under a safe operating temperature range.

All the protection mechanisms mentioned above combine to provide a complete protecting scenario in the motor system and avoid any possible damages and guarantee under a correct and safe operation.

### Block Diagram



**Figure.1**

**Pin Connection**

**Figure.2**
**Marking Distinguish**

**Figure.3**
**Pin Descriptions**

Name	I/O	FD2257H	Description
VDD	P	1	Positive Power Supply
NO	O	2	Driver Output 1
SO	O	3	Driver Output 2
VSS	G	4	Ground

Legend: I=input, O=output, I/O=input/output, P=power supply, G=ground

**Functional Descriptions**

Refer to the block diagram (Figure.1), FD2257H is composed of the following building blocks:

- Bias generator

The bias generator provides precise, temperature- and process-insensitive bias references for the analog blocks. These references guarantee proper operation of the IC under all conditions specified in this specification.

- Oscillator

The built-in oscillator provides the clock signal for the digital control logic.

- Power On Reset

Used to detect the power-up ramp and reset the digital circuits to achieve correct operation as soon as the power is ready.

- Chopper Amplifier

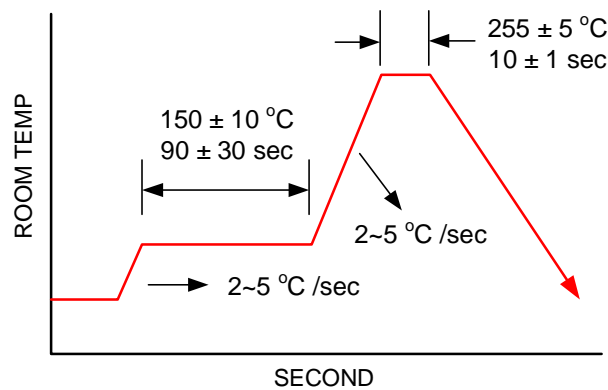
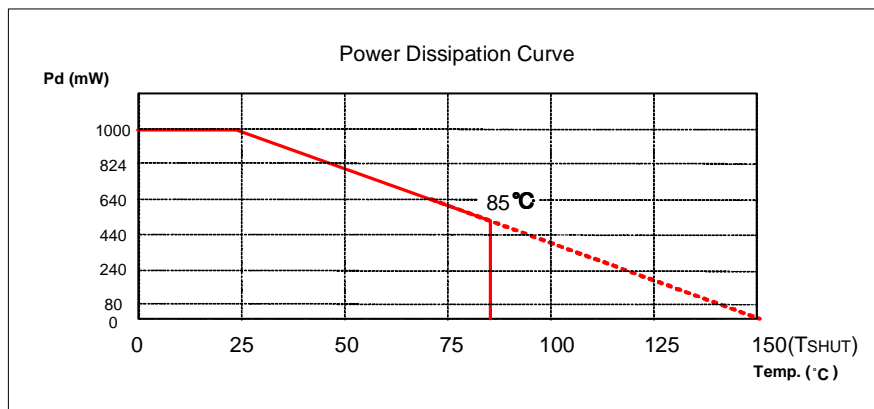
To achieve a higher magnetic sensitivity the chopper amplifier structure is adopted in this design. Use of this structure dynamically removes both the offset and flicker noise at the same time.

- Digital Control Logic

- Hall sensor part – generates magnetic pole signals from the Hall-effect sensor.
- Driver part – generates switching signals to the H-Bridge MOS driver.
- Timer part – generates an interval of time when rotor locked event is occurred.

**Absolute Maximum Ratings**

Parameter	Symbol	Conditions	Values			Unit
			min.	typ.	max.	
Operating Temperature	$T_{OP}$	-	-40		85	°C
Storage Temperature	$T_{ST}$	-	-55		150	°C
DC Supply Voltage	$V_{DD}$	-			29	V
Output Voltage (NO, SO)	$V_{OUT}$	-			$V_{DD}+0.3V$	V
Supply Current	$I_{DD}$	-			5	mA
Continuous Current	$I_{O(CONT)}$				300	mA
Hold Current	$I_{O(HOLD)}$				800	mA
Peak Current	$I_{O(PEAK)}$	<100 $\mu$ s			1000	mA
Junction temperature	$T_J$				170	°C
Power Dissipation	$P_D$	SIP-4L			1000	mW
Thermal Resistance	$\theta_{JC}$	SIP-4L		100		°C/W
Thermal Resistance	$\theta_{JA}$	SIP-4L		125		°C/W
Magnetic Flux Density	B				Unlimited	Gauss
IR-Reflow Lead Temperature	$T_P$	10sec			260	°C


**IR-ReFlow Soldering Condition**

**Recommended Operating Conditions**

Parameter	Symbol	Conditions	Values			Unit
			min.	typ.	max.	
Supply Voltage	$V_{DD}$	-	4.0		28	V
Operating Temperature Range	$T_a$	-	-40		85	°C

**Electrical Characteristics  $T_a=25^\circ\text{C}$  (unless otherwise specified)**

Parameter	Symbol	Conditions	Values			Unit
			min.	typ.	max.	
Average Supply Current(no load)	$I_{DD}$	$V_{DD} = 24\text{V}$		2.5		mA
On resistance ( $R_{PMOS}+R_{NMOS}$ )	$R_{DS(ON)}$	$V_{DD} = 5\text{V}$		3.5		$\Omega$
		$V_{DD} = 24\text{V}$		2.0		
Thermal Shutdown Threshold	$T_{SHUT}$		150			°C
Locked Rotor Period	$T_{ON}$			0.4		s
Locked Rotor Period	$T_{OFF}$			4.1		s

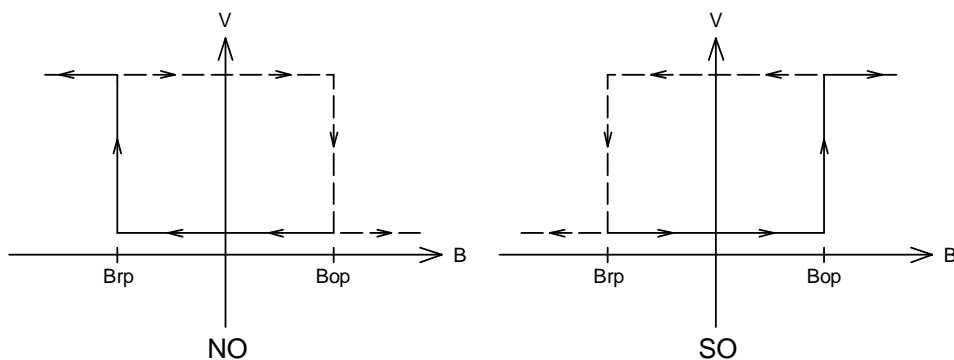
**Magnetic Characteristics**

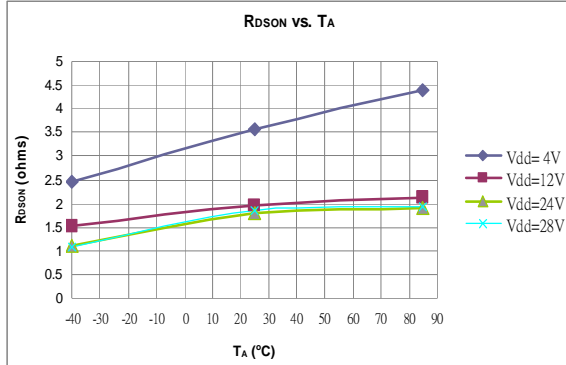
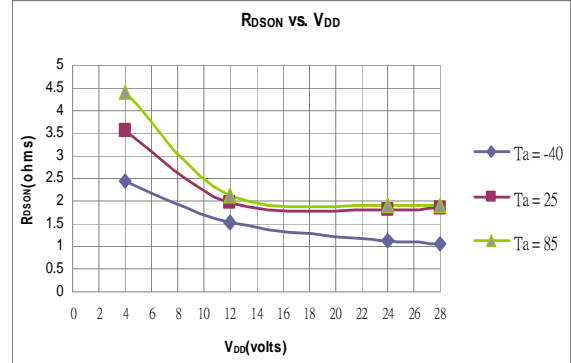
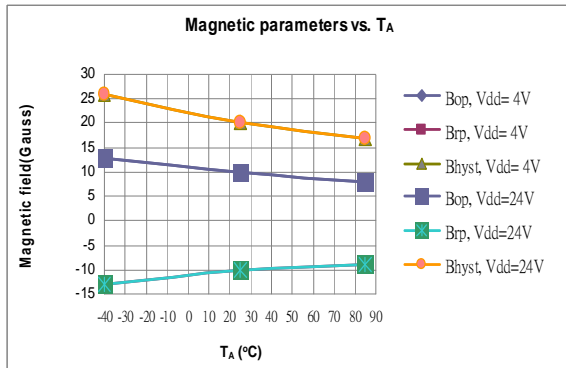
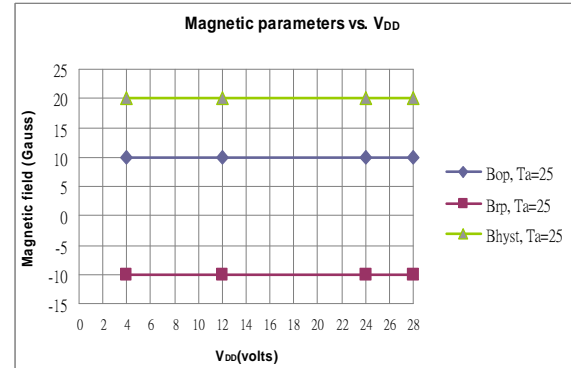
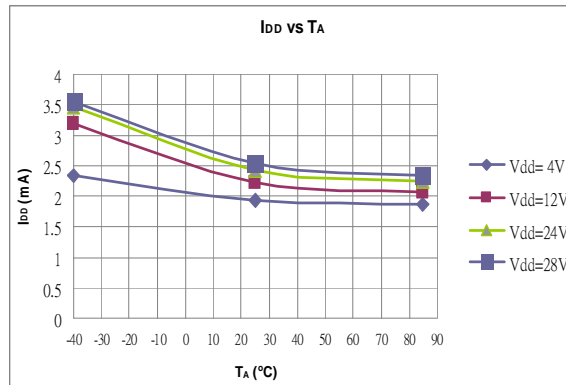
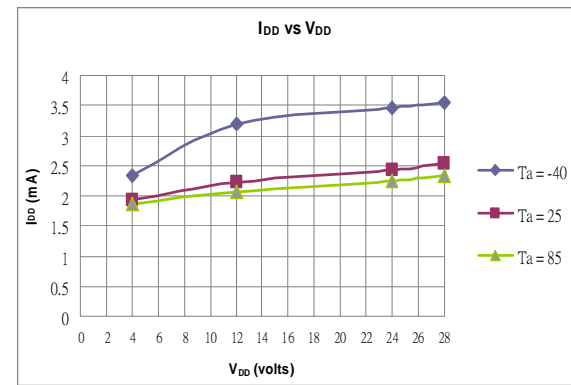
Parameter	Symbol	Conditions	Values			Unit
			min.	typ.	max.	
Operate Points	$B_{OP}$		5	25	50	G
Release Points	$B_{RP}$		-5	-25	-50	G
Hysteresis	$B_{HYS}$			50		G

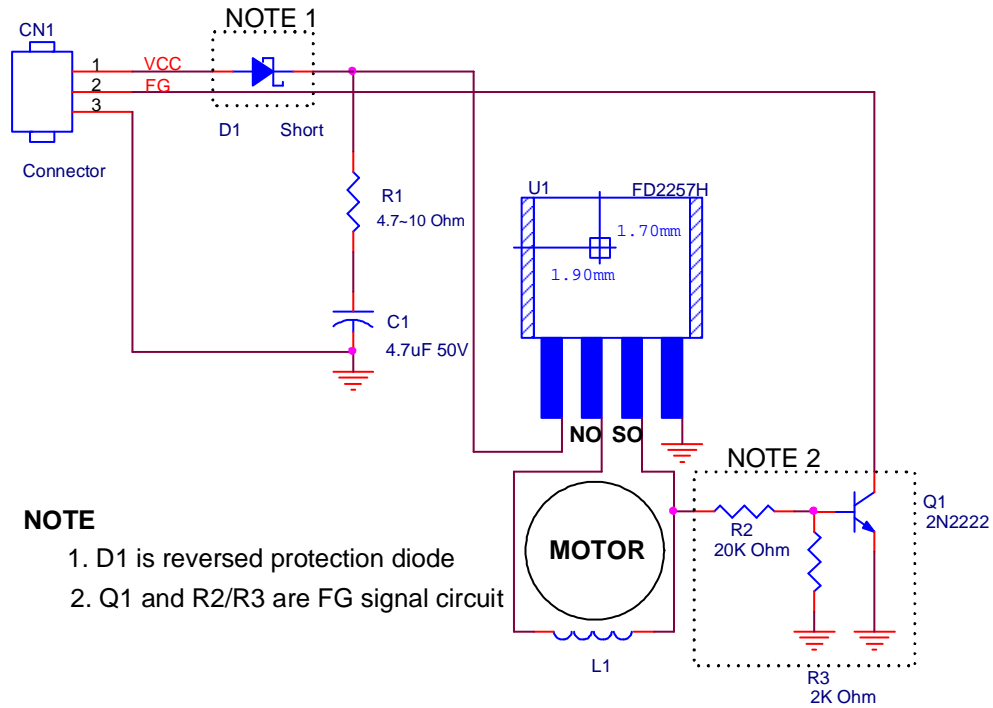
**Driver output vs. Magnetic Pole**

Parameter	Test Conditions	NO	SO
North pole	$B < B_{rp}$	High	Low
South pole	$B > B_{op}$	Low	High

**Note:** The magnetic pole is applied facing the branded side of the package

**Hysteresis Characteristics**


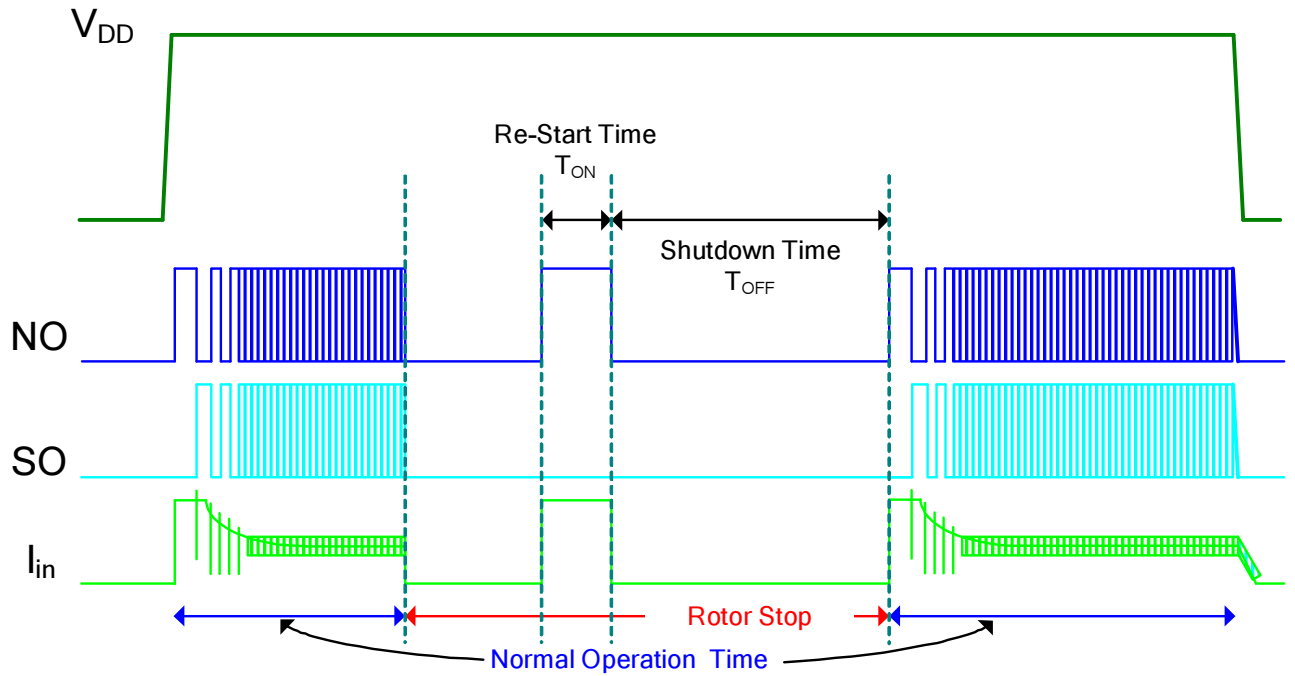
**Performance Graphs**

**Figure.4**

**Figure.5**

**Figure.6**

**Figure.7**

**Figure.8**

**Figure.9**

**Application Circuit Reference**

**Figure.10 FD2257H Typical Application Circuits**
**Note:**

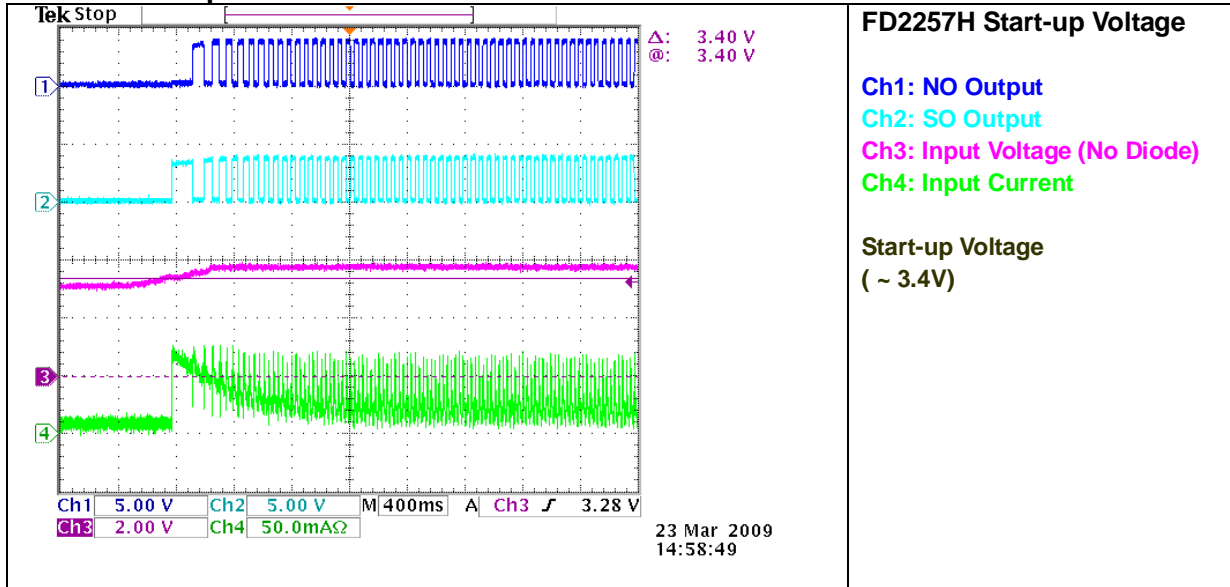
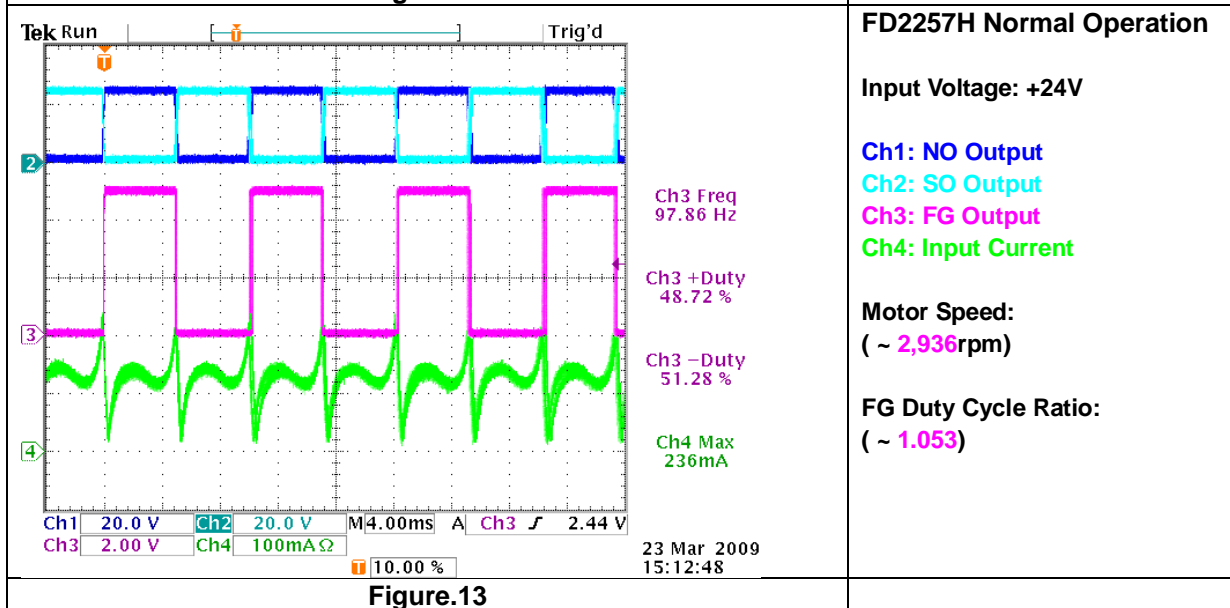
Must use least  $C1=1\mu F$ (electrolytic) capacitor &  $R1=4.7\sim 10$  Ohm for the decoupling between  $V_{DD}$  and  $V_{SS}$  and place the capacitor as close to the IC as possible.



**Output Waveforms Description**



**Figure.11**

**FD2257H Output Waveforms Measurement**

**Figure.12**

**Figure.13**



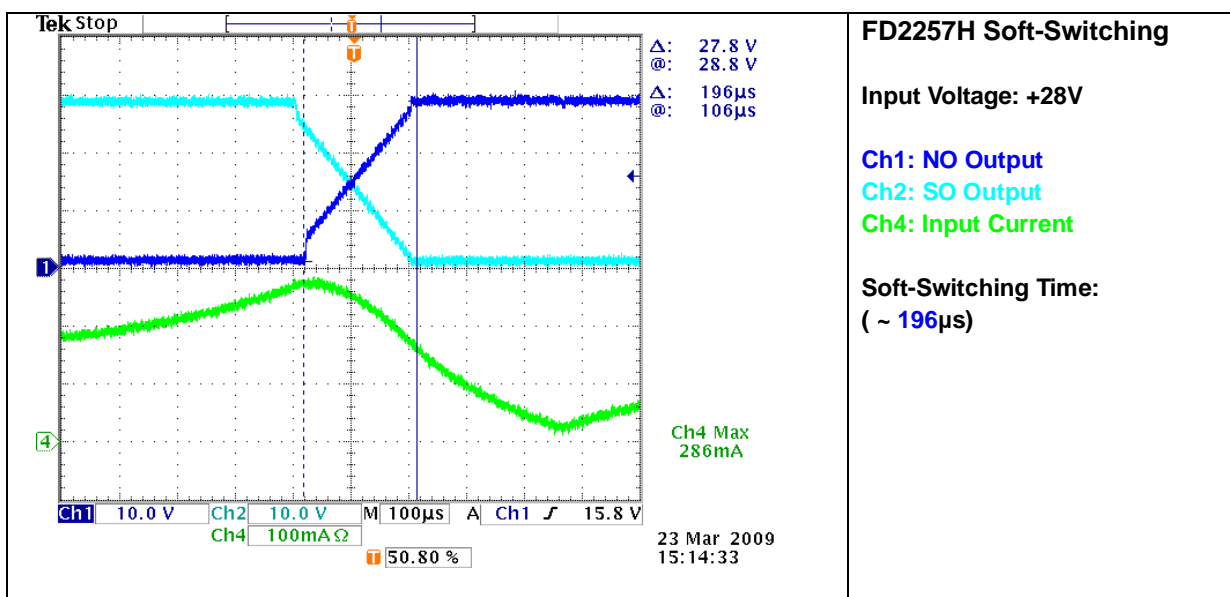


Figure.14

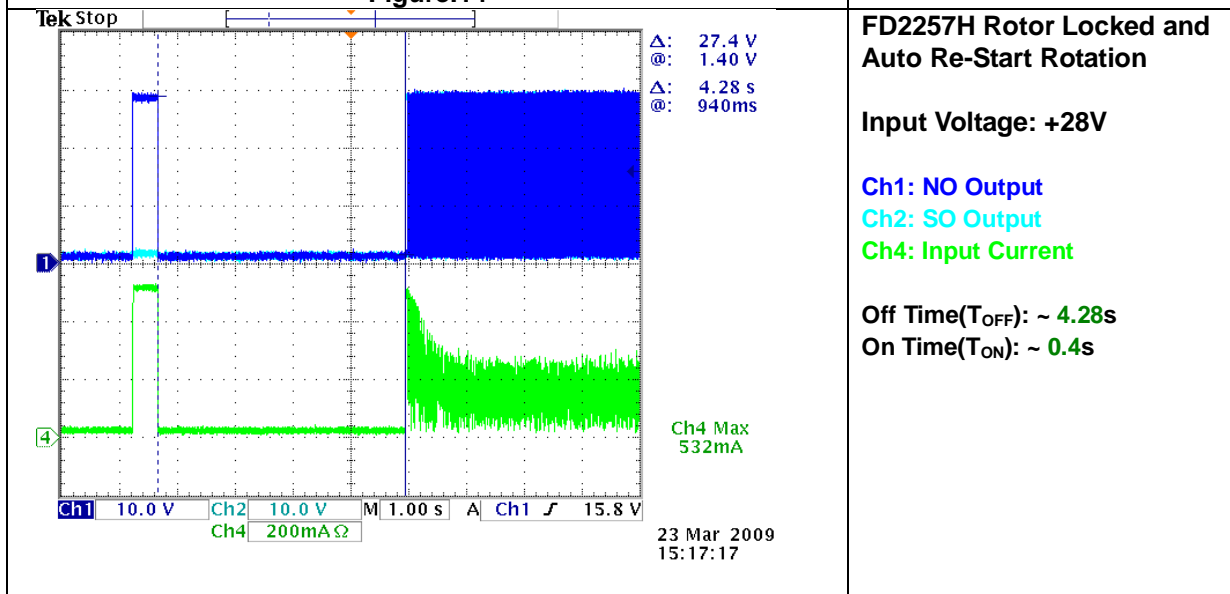


Figure.15

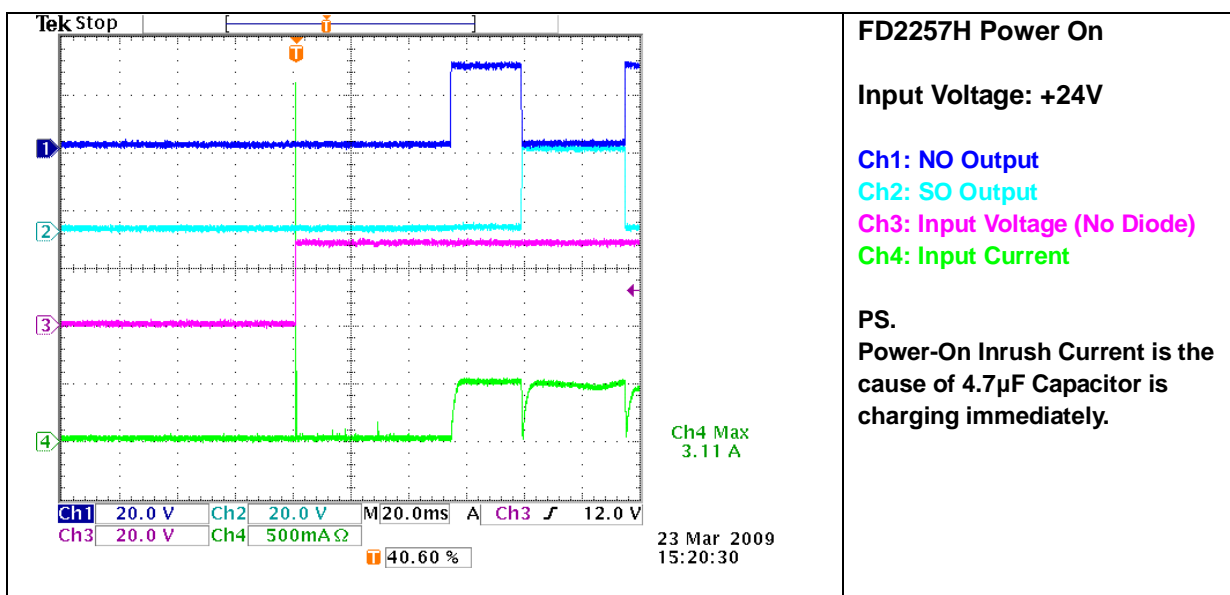


Figure.16

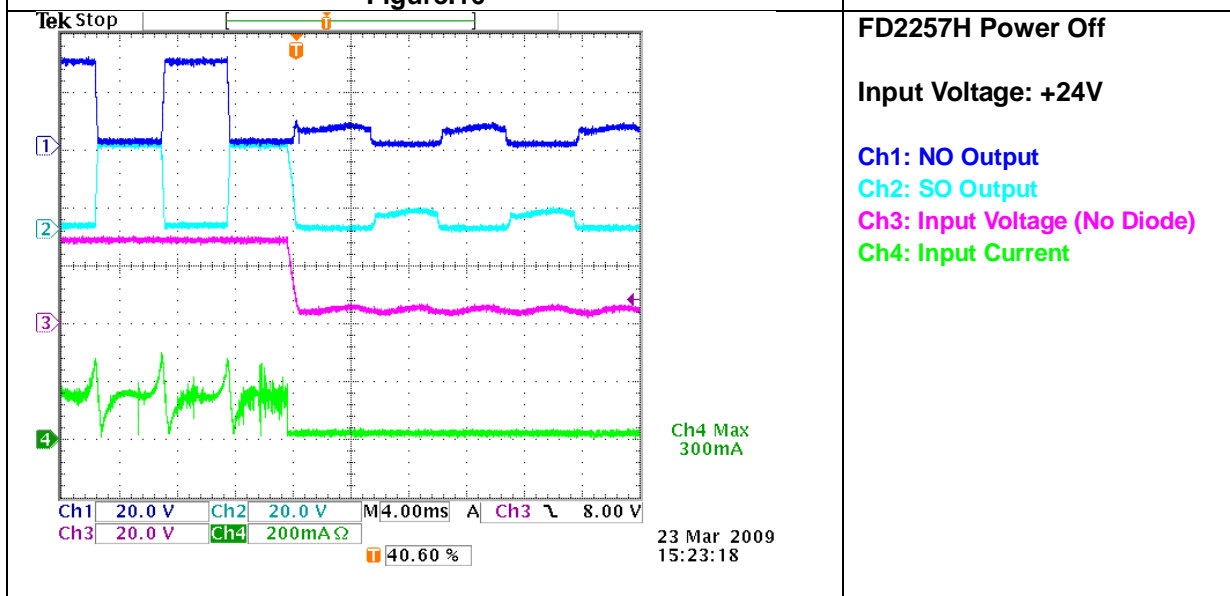
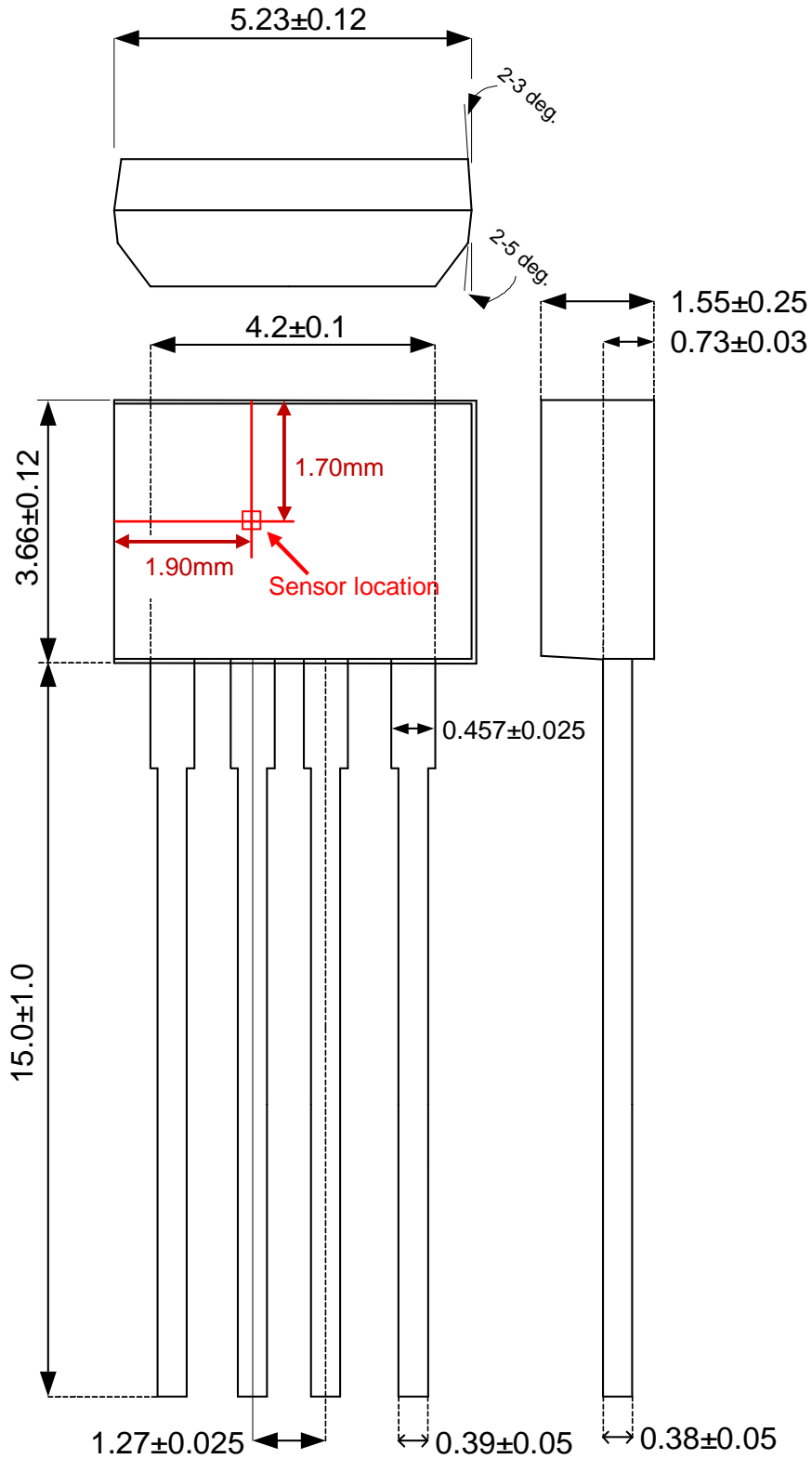
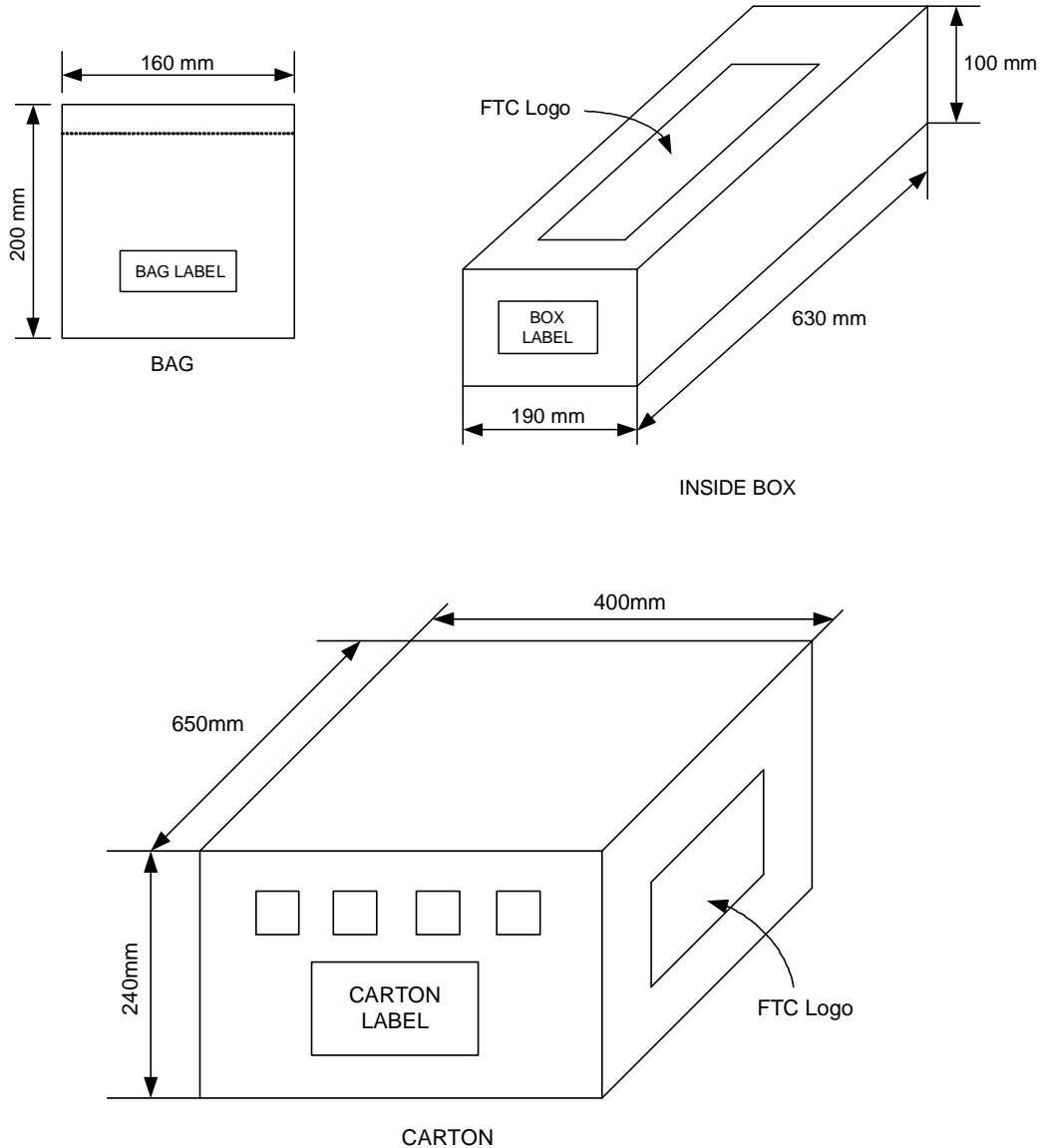


Figure.17



Package Dimension (Unit: mm)  
SIP-4L(Halogen Free)



**Packing Specification**
**BAG & BOX DIMANSION**

**Packing Quantity Specifications**

1000 EA / 1 BAG

20 BAGS / 1 INSIDE BOX

4 INSIDE BOXES / 1 CARTON

**Order Information**

Part Number	Operating Temperature	Package	Description	MOQ	MSL
FD2257H-G1	-40 °C to +85 °C	SIP-4L	±50G (B)	1,000 EA / BAG	3